

Wed.	(C 21.1-.5,.8) 2.2.3 Using Gauss, (T2 Numerical Quadrature, 1.3 Integral Calc)	HW1
Thurs		
Fri.	(C21.1-.5,.8) 2.2.3-.2.4 Using Gauss	

## *Using Gauss's Law*

# Last Time

Not just  $\vec{E}_{net} = \int_{charge} \frac{1}{4\pi\epsilon_0} \frac{\hat{r}}{r^2} dq$

But also  $\oint_S \vec{E} \cdot d\vec{a} = \frac{1}{\epsilon_0} Q_{enc}$

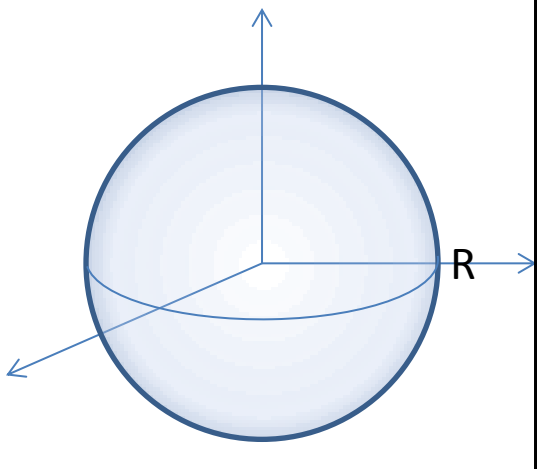
Or  $\lim_{Vol \rightarrow 0} \frac{\oint_S \vec{E} \cdot d\vec{a}}{Vol} = \lim_{Vol \rightarrow 0} \frac{1}{\epsilon_0} \frac{Q_{enc}}{Vol}$

$$Div \vec{E} = \frac{1}{\epsilon_0} \rho$$

$$\vec{\nabla} \cdot \vec{E} = \frac{1}{\epsilon_0} \rho$$

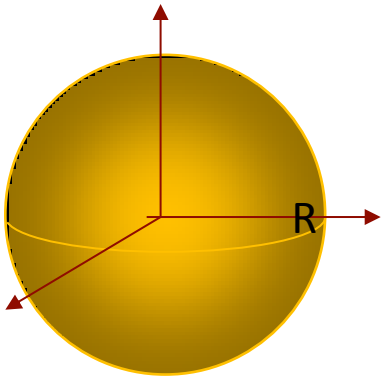
**Example** Hollow, spherical shell of radius  $R$  with  $Q$  uniformly distributed over the surface.

Field inside and out.



**Example** Solid sphere of radius R with varying charge density:  $\rho(r') = \rho_0 \frac{r'^3}{R^3}$

Field inside and out.



## Exercise

### ***Uniformly-Charged Rod***

A thin rod of length  $L$  has a positive charge  $Q$  distributed uniformly along its length.

- 1. Field Geometry.** Use a *symmetry* argument to determine the *direction* of the electric field near the center of the rod.
- 2. Choosing the Gaussian bubble.** What shape of Gaussian surface can you draw so that each part is either perpendicular or parallel to the electric field?
- 3. Doing the Math.** Use Gauss's law to find the magnitude of the electric field at a radial distance  $r$  from the rod near its center.

## Exercise

### ***Solid Uniformly-Charged Sphere (inside and out)***

A solid sphere of radius  $R$  has a positive charge  $Q$  distributed uniformly throughout its volume.

- 1. Field Geometry.** Use a symmetry argument to determine the direction of the electric field.
- 2. Choosing a Gaussian Bubble.** What shape of Gaussian surface can you draw so that each part is either perpendicular or parallel to the electric field?
- 3. Doing the Math.** Use Gauss's law to find the magnitude of the electric field at a distance  $r$  from the center of the sphere for:

# Curl of E

In Spherical Coordinates:  $\vec{E} = \frac{1}{4\pi\epsilon_0} \frac{q}{r^2} \hat{r} = E_r \hat{r}$

$$\vec{\nabla} \times \vec{E} = \frac{1}{r \sin \theta} \left[ \frac{\partial}{\partial \theta} (\sin \theta E_\phi) - \frac{\partial}{\partial \phi} E_\theta \right] \hat{r} + \frac{1}{r} \left[ \frac{1}{\sin \theta} \frac{\partial}{\partial \phi} (E_r) - \frac{\partial}{\partial r} (r E_\phi) \right] \hat{\theta} + \frac{1}{r} \left[ \frac{\partial}{\partial r} (r E_\theta) - \frac{\partial}{\partial \theta} (r E_r) \right] \hat{\phi}$$

$$\vec{\nabla} \times \vec{E} = \frac{1}{r} \left[ \frac{1}{\sin \theta} \frac{\partial}{\partial \phi} (E_r) \right] \hat{\theta} - \frac{1}{r} \left[ \frac{\partial}{\partial \theta} (r E_r) \right] \hat{\phi} = 0 \quad \text{A little too easy}$$

In Cartesian Coordinates:

$$\vec{E}_1(\vec{r}) = \frac{q}{4\pi\epsilon_0} \frac{\vec{r}}{r^3} = \frac{q}{4\pi\epsilon_0} \frac{[(x-x')\hat{x} + (y-y')\hat{y} + (z-z')\hat{z}]}{[(x-x')^2 + (y-y')^2 + (z-z')^2]^{3/2}}$$

$$\vec{\nabla} \times \vec{E}_1 = \left( \frac{q}{4\pi\epsilon_0} \right) \begin{vmatrix} \hat{x} & \hat{y} & \hat{z} \\ \frac{\partial}{\partial x} & \frac{\partial}{\partial y} & \frac{\partial}{\partial z} \\ \frac{|x-x'|}{[x-x']^2 + [y-y']^2 + [z-z']^2}^{3/2} & \frac{|y-y'|}{[ ]^{3/2}} & \frac{|z-z'|}{[ ]^{3/2}} \end{vmatrix}$$

$$\frac{\partial}{\partial y} \left\{ \frac{(z-z')}{[ ]^{3/2}} \right\} - \frac{\partial}{\partial z} \left\{ \frac{(y-y')}{[ ]^{3/2}} \right\} = (z-z') \frac{(-\frac{3}{2})2(y-y')}{[ ]^{5/2}} - (y-y') \frac{(-\frac{3}{2})2(z-z')}{[ ]^{5/2}} = 0 \quad \text{Etc.}$$