Mon.	(C 17) 12.1.11.2, 12.3.1 E to B; 5.1.11.2 Lorentz Force Law: fields and forces	
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#### Force between stationary charges

(Coulomb's Law: Eq'n 2.1)





"The entire theory of classical electrodynamics is contained in that equation...but you see why I preferred to start out with Coulomb's law." - Griffiths

## Force between moving charges



But who's moving how fast is all relative

Note: extremely asymmetric between two charges; reciprocity (Newton's 3<sup>rd</sup>) does not hold

Principle: Laws of Physics should be the same in all inertial frames of reference

Old frame-transformation math:\_-

$$\vec{v}_{ball-you} = \vec{v}_{ball-me} + \vec{v}_{me-you}$$
$$\Delta \vec{x}_{ball-you} = \Delta \vec{x}_{ball-me} + \vec{v}_{me-you} \cdot \Delta t$$

laws of E&M referenced an absolute speed, not speed relative to preferred frame

**Observations**:

Charge moving near stationary magnet feels magnetic force; charge stationary near moving magnet feels...?

One of the three must go

Key to new frame-transformation math:

Speed of light is measured to be the \_\_\_\_\_ same in all reference frames

New frame-transformation math derived – light clocks and meter sticks



New frame-transformation math derived – light clocks and meter sticks

$$L_{w,s} = \frac{L_{w,c}}{\sqrt{1 - \left(\frac{\nu}{c}\right)^2}} = \gamma L_{w,c} \qquad \Delta t_{w,s} \sqrt{1 - \left(\frac{\nu}{c}\right)^2} = \frac{1}{\gamma} \Delta t_{w,s}$$

Think of the ladder and barn problem. Say the Farmer's got hold of the ladder and he's going to run at the barn.

#### Crash Course in Special Relativity Galilean Transformation Corrected



I'm in a train watching a pool game. I see the ball role a distance  $\Delta x_{ball.table}$  to the pocket. I see it's taking time  $\Delta t_{ball.table}$  to get there. Meanwhile, the train and I are rolling through the station in the same direction at speed **v**. You, standing in the station, see all this happen. *Classically, you'd* imagine that with *my* yard stick, *I'd* measure the ball rolling a distance

$$\Delta x_{ball.table} = \Delta x_{ball_station} - v\Delta t_{ball.station}$$

But to phrase that in terms of what *I* in the train would measure, " $\Delta x_{ball.table}$ " =  $\frac{1}{\gamma} \Delta x_{ball.table}$ so,  $\frac{1}{\gamma} \Delta x_{ball.table} = \Delta x_{ball.station}$ -v $\Delta t_{ball.station}$ or,  $\Delta x_{ball.table} = \gamma (\Delta x_{ball.station} - v \Delta t_{ball.station})$ 

Then again, I'd imagine with your yardstick you'd measure the ball rolling a distance

 $\begin{array}{l} & "\Delta x_{ball.station}" = \Delta x_{ball\_table} + v\Delta t_{ball.table} \\ & \text{But in terms of what you in the station would measure,} \\ & \text{so,} \quad \Delta xball\__{station} = \gamma(\Delta x_{ball\_table} + v\Delta t_{ball.table}) \\ & \text{Note: both observers measure,} \\ & \text{Note: both observers measure,} \\ & \text{Son the station} = \gamma(\Delta x_{ball\_table} + v\Delta t_{ball.table}) \\ & \text{Son the station} = \gamma(\Delta x_{ball\_table} + v\Delta t_{ball.table}) \\ & \text{Son the station} = \gamma(\Delta x_{ball\_table} + v\Delta t_{ball.table}) \\ & \text{Son the station} = \gamma(\Delta x_{ball\_table} + v\Delta t_{ball.table}) \\ & \text{Son the station} = \gamma(\Delta x_{ball\_table} + v\Delta t_{ball.table}) \\ & \text{Son the station} = \gamma(\Delta x_{ball\_table} + v\Delta t_{ball.table}) \\ & \text{Son the station} = \gamma(\Delta x_{ball\_table} + v\Delta t_{ball.table}) \\ & \text{Son the station} = \gamma(\Delta x_{ball\_table} + v\Delta t_{ball.table}) \\ & \text{Son the station} = \gamma(\Delta x_{ball\_table} + v\Delta t_{ball.table}) \\ & \text{Son the station} = \gamma(\Delta x_{ball\_table} + v\Delta t_{ball.table}) \\ & \text{Son the station} = \gamma(\Delta x_{ball\_table} + v\Delta t_{ball.table}) \\ & \text{Son the station} = \gamma(\Delta x_{ball\_table} + v\Delta t_{ball.table}) \\ & \text{Son the station} = \gamma(\Delta x_{ball\_table} + v\Delta t_{ball.table}) \\ & \text{Son the station} = \gamma(\Delta x_{ball\_table} + v\Delta t_{ball.table}) \\ & \text{Son the station} = \gamma(\Delta x_{ball\_table} + v\Delta t_{ball.table}) \\ & \text{Son the station} = \gamma(\Delta x_{ball\_table} + v\Delta t_{ball.table}) \\ & \text{Son the station} = \gamma(\Delta x_{ball\_table} + v\Delta t_{ball.table}) \\ & \text{Son the station} = \gamma(\Delta x_{ball\_table} + v\Delta t_{ball\_table}) \\ & \text{Son the station} = \gamma(\Delta x_{ball\_table} + v\Delta t_{ball\_table}) \\ & \text{Son the station} = \gamma(\Delta x_{ball\_table} + v\Delta t_{ball\_table}) \\ & \text{Son the station} = \gamma(\Delta x_{ball\_table} + v\Delta t_{ball\_table}) \\ & \text{Son the station} = \gamma(\Delta x_{ball\_table} + v\Delta t_{ball\_table}) \\ & \text{Son the station} = \gamma(\Delta x_{ball\_table} + v\Delta t_{ball\_table}) \\ & \text{Son the station} = \gamma(\Delta x_{ball\_table} + v\Delta t_{ball\_table}) \\ & \text{Son the station} = \gamma(\Delta x_{ball\_table} + v\Delta t_{ball\_table}) \\ & \text{Son the station} = \gamma(\Delta x_{ball\_table} + v\Delta t_{ball\_table}) \\ & \text{Son the station} = \gamma(\Delta x_{ball\_table} + v\Delta t_{ball\_table}) \\ & \text{Son t$ 

**Consistent only if**  $\Delta t_{ball.station} = \gamma (\Delta t_{ball.table} + \frac{v}{c^2} \Delta x_{ball.table})$  $\Delta t_{ball.table} = \gamma (\Delta t_{ball.station} - \frac{v}{c^2} \Delta x_{ball.station})$  ball.station " =  $\frac{-}{\gamma} \Delta x_{ball.station}$ Note: both observers measure distances as 'proper' lengths of their sticks, but neither is a equidistant to the two eventsneither measures proper time

#### Crash Course in Special Relativity Galilean Transformation Corrected



I'm in a train watching a pool game. I see the ball role a distance  $\Delta x_{ball.table}$  to the pocket. I see it's taking time  $\Delta t_{ball.table}$  to get there. Meanwhile, the train and I are rolling through the station in the same direction at speed **v**. You, standing in the station, see all this happen.

$$v_{ball.station} = \frac{\Delta x_{ball.station}}{\Delta t_{ball.station}} = \frac{\gamma(\Delta x_{ball.table} + v\Delta t_{ball.table})}{\gamma(\Delta t_{ball.table} + \frac{v}{c^2}\Delta x_{ball.table})}$$
Some algebra later,
$$v_{ball_station} = \frac{v_{ball_stable}}{1 + \frac{vv_{ball_stable}}{c^2}}$$

**Or renaming v = v**<sub>table.station</sub>

$$v_{ball\_station} = \frac{v_{ball\_table} + v_{table\_station}}{1 + \frac{v_{table\_station}v_{ball\_table}}{c^2}}$$

New frame-transformation math derived – light clocks and meter sticks Example

$$v_{ball station} = \frac{v_{ball table} + v_{table station}}{1 + \frac{v_{table station}v_{ball table}}{c^2}}$$

Lab frame: you and I see an electrically neutral wire (all be it, with the electrons moving)



 $v_e$  = electron velocity measured by us in the "lab frame"

Stationary charge

$$\vec{\mathbf{q}} \qquad \vec{\vec{F}}_{q \leftarrow wire} = q\vec{\vec{E}}_{wire}$$
$$\vec{\vec{E}}_{wire} = \vec{\vec{E}}_{+} + \vec{\vec{E}}_{-} = \frac{1}{4\pi\varepsilon_{o}}\frac{2\lambda_{+}}{r} + \frac{1}{4\pi\varepsilon_{o}}\frac{2\lambda_{-}}{r} = \frac{1}{4\pi\varepsilon_{o}}\frac{2\lambda_{+}}{r} + \frac{1}{4\pi\varepsilon_{o}}\frac{-2\lambda_{+}}{r} = 0$$

Lab frame: you and I see an electrically neutral wire (all be it, with the electrons moving)



 $v_{a}$  = electron velocity measured by us in the "lab frame"

Moving charge

$$\vec{\mathbf{q}} \xrightarrow{\mathbf{V}_{\mathbf{q}}} \vec{F}_{q \leftarrow wire} = \mathcal{E}$$

Charge's frame:

Chain of positive atoms moving backwards at  $v_{atoms} = -v_q$ So spacing seen by charge is related to their stationary, "proper" separation (as seen in lab) by

$$\Delta x_{atom}' = \frac{\Delta x_{atom.\,proper}}{\gamma_{q'}} = \frac{\Delta x_{lab}}{\gamma_{q'}} = \Delta x_{lab} \sqrt{1 - \left(\frac{v_q}{c}\right)}$$

Or charge density appears compressed to

 $\lambda_{+}' = \frac{\gamma_{q'}e}{\Delta x_{lab}}$ Chain of electrons moving forward at only  $v_{e}' = \frac{v_{e} - v_{q}}{1 - \frac{v_{e}v_{q}}{c^{2}}}$ 

So spacing seen by charge is related to their stationary, "proper" separation (not seen in lab) by

$$\Delta x_{e}' = \frac{\Delta x_{e, proper}}{\gamma_{e'}} \quad \text{where} \quad \gamma_{e'} = \frac{1}{\sqrt{1 - \left(\frac{v_{e'}}{c}\right)^2}}$$

Similarly, separation in *lab* frame relates to "proper" separation (seen in electrons' rest frame)

$$\Delta x_{e.\,proper} = \gamma_e \Delta x_{lab} \text{ where } \gamma_e = \frac{1}{\sqrt{1 - \left(\frac{v_e}{c}\right)^2}} \text{ Combined: } \Delta x_e' = \frac{\gamma_e \Delta x_{lab}}{\gamma_{e'}}$$
So,  $\lambda_-' = \frac{-\gamma_{e'} e}{\gamma_e \Delta x_{lab}} = \frac{-\gamma_{e'}}{\gamma_e \gamma_{q'}} \lambda_+'$ 

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Charge's frame:  

$$\lambda_{+}' = \frac{\gamma_{q}e}{\Delta x_{lab}} \qquad \qquad \lambda_{-}' = \frac{-\gamma_{e}e}{\gamma_{e}\Delta x_{lab}} = \frac{-\gamma_{e'}}{\gamma_{e}\gamma_{q'}}\lambda_{+}'$$

$$\lambda_{-}' = \text{ions' charge density} \qquad \qquad \lambda_{-}' = \frac{-\gamma_{e'}}{\gamma_{e}\Delta x_{lab}} = \frac{-\gamma_{e'}}{\gamma_{e}\gamma_{q'}}\lambda_{+}'$$

$$\lambda_{-}' = \text{ions' charge density} \qquad \qquad \lambda_{-}' = \text{electrons' charge density} \qquad \qquad \lambda_{-}' = \text{electrons' meter} \qquad \qquad \lambda_{-}' = \frac{\gamma_{e'}}{\gamma_{e'}}\lambda_{+}' \qquad \qquad \lambda_{-}'$$

Transformation from rest frame requires factor of  $\gamma/\gamma^2 = 1/\gamma$ 

$$\vec{F}_{q \leftarrow wire} = q v_q \, \frac{\mu_o}{4\pi} \frac{2I}{r}$$



Depends on *observer's* perception of *source* charge's velocity and acceleration

Also depends on observer's perception of recipient charge's velocity

#### Magnetic force



#### Cyclotron Motion in a Uniform Magnetic Field $\frac{d\vec{p}}{dt} = \vec{F} = q\left(\vec{E} + \vec{v} \times \vec{B}\right)$ **Book's Example** $m\frac{d\vec{v}}{dt} = q\left(\vec{E} + \vec{v} \times \vec{B}\right)$ In general $\vec{B}$ $m \begin{cases} \frac{dv_x}{dt} \\ \frac{dv_y}{dt} \\ \frac{dv_z}{dt} \end{cases} = q \begin{pmatrix} E_x \\ E_y \\ E_z \end{pmatrix} + \begin{vmatrix} \hat{x} & \hat{y} & \hat{z} \\ v_x & v_y & v_z \\ B_x & B_y & B_z \end{vmatrix} = q \begin{cases} E_x + v_y B_z - v_z B_y \\ E_y + v_z B_x - v_x B_z \\ E_z + v_x B_y - v_y B_x \end{pmatrix}$ **Guess Solution Forms** $\frac{dv_z}{dt} = \frac{qE}{m} - \frac{qB}{m}v_y \qquad v_z(t) = C_1 \cos(\omega t) + C_2 \sin(\omega t)$ $v_z(t) = C_2 \cos(\omega t) + C_2 \sin(\omega t)$ $dv_{y}$ m Take next derivative $\frac{d^2 v_y}{dt^2} = \frac{qB}{r} \frac{dv_z}{dv_z}$ dt $v_{y}(t) = C_{3}\cos(\omega t) + C_{4}\sin(\omega t) + \frac{E}{2}$ Cross $\frac{d^2 v_z}{dt^2} =$ $qB dv_y$ Plug in m dt $\frac{dv_{y}}{dt} = \frac{qB}{m}v_{z}$ substitute $\frac{d^2 v_y}{dt^2} = \frac{qB}{m} \left( \frac{qE}{m} - \frac{qB}{m} v_y \right)^2 \frac{d^2 v_z}{dt^2} = -\left( \frac{qB}{m} \right)^2 v_z$ $\omega(-C_3\sin(\omega t) + C_4\cos(\omega t)) = \frac{\overline{qB}}{\overline{qB}}(C_1\cos(\omega t) + C_2\sin(\omega t))$ $\frac{d^2 v_y}{dt^2} = \frac{q^2 BE}{m^2} - \left(\frac{qB}{m}\right)^2 v_y$ т $\omega = \frac{qB}{c_1} - C_3 = C_2 \quad C_4 = C_1$ Compare terms and conclude

$$\begin{aligned} & \begin{array}{l} \hline \textbf{Cyclotron Motion in a Uniform Magnetic Field} \\ \hline \vec{F} = q(\vec{E} + \vec{v} \times \vec{B}) \\ v_z(t) = C_1 \cos(\omega t) + C_2 \sin(\omega t) \quad v_y(t) = C_1 \sin(\omega t) - C_2 \cos(\omega t) + \frac{E}{B} \quad \vec{B} \quad \vec{P} \\ \hline \textbf{Where } \omega = \frac{qB}{m} \\ \hline \textbf{For position components, integrate} \\ z(t) = \frac{C_1}{\omega} \sin(\omega t) - \frac{C_2}{\omega} \cos(\omega t) + C_5 \quad y(t) = -\frac{C_1}{\omega} \cos(\omega t) - \frac{C_2}{\omega} \sin(\omega t) + \frac{E}{B} t + C_6 \\ \hline \textbf{Impose Initial Conditions} \\ z(0) = -\frac{C_2}{\omega} + C_5 = 0 \quad \text{Start at origin} \quad y(0) = -\frac{C_1}{\omega} + C_6 = 0 \\ C_5 = \frac{C_2}{\omega} \quad C_6 = \frac{C_1}{\omega} \\ z(t) = \frac{C_1}{\omega} \sin(\omega t) + \frac{C_2}{\omega} (1 - \cos(\omega t)) \quad y(t) = \frac{C_1}{\omega} (1 - \cos(\omega t)) - \frac{C_2}{\omega} \sin(\omega t) + \frac{E}{B} t \end{aligned}$$

$$\begin{aligned} & \begin{array}{l} \hline \textbf{Cyclotron Motion in a Uniform Magnetic Field} \\ \hline F = q(\vec{E} + \vec{v} \times \vec{B}) \\ v_z(t) = C_1 \cos(\omega t) + C_2 \sin(\omega t) & v_y(t) = C_1 \sin(\omega t) - C_2 \cos(\omega t) + \frac{E}{B} & \vec{B} \\ & \text{where } \omega = \frac{qB}{m} & \vec{v} \\ \hline \textbf{Impose Initial Conditions} \\ \hline \textbf{Initial position: } (0,0) \\ z(t) = \frac{C_1}{\omega} \sin(\omega t) + \frac{C_2}{\omega} (1 - \cos(\omega t)) & y(t) = \frac{C_1}{\omega} (1 - \cos(\omega t)) - \frac{C_2}{\omega} \sin(\omega t) + \frac{E}{B} t \\ \hline \textbf{Initial Velocity: } \vec{v}(0) = 0 \\ v_z(0) = C_1 \cos(0) + C_2 \sin(0) & v_y(0) = C_1 \sin(0) - C_2 \cos(0) + \frac{E}{B} \\ v_z(0) = C_1 \cos(0) + C_2 \sin(0) & v_y(0) = -C_2 + \frac{E}{B} = 0 & C_2 = \frac{E}{B} \\ \hline \textbf{So.} \\ v_z(t) = \frac{E}{B} \sin(\omega t) & v_y(t) = \frac{E}{\omega B} (1 - \cos(\omega t)) \\ z(t) = \frac{E}{\omega B} (1 - \cos(\omega t)) & y(t) = \frac{E}{\omega B} (\omega t - \sin(\omega t)) \end{aligned}$$

Cyclotron Motion in a Uniform Magnetic Field  

$$\vec{F} = q(\vec{E} + \vec{v} \times \vec{B})$$

$$v_z(t) = C_1 \cos(\omega t) + C_2 \sin(\omega t) \quad v_y(t) = C_1 \sin(\omega t) - C_2 \cos(\omega t) + \frac{mE}{\omega} \quad \vec{B}$$
where  $\omega = \frac{qB}{m}$ 
Impose Initial Conditions  
Initial position: (0,0)  

$$z(t) = \frac{C_1}{\omega} \sin(\omega t) + \frac{C_2}{\omega} (1 - \cos(\omega t)) \qquad y(t) = \frac{C_1}{\omega} (1 - \cos(\omega t)) - \frac{C_2}{\omega} \sin(\omega t) + \frac{mE}{\omega} t$$
Initial Velocity:  $\vec{v}(0) = (E \mid B)\hat{y}$   
 $v_z(0) = C_1 \cos(0) + C_2 \sin(0)$   
 $v_z(0) = C_1 \cos(0) + C_2 \sin(0)$   
 $v_z(0) = C_1 - \frac{mE}{\omega} = \frac{E}{B}$ 

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Cyclotron Motion in a Uniform Magnetic Field



Cyclotron Motion in a Uniform Magnetic Field

 $\vec{F}_{mag} = \vec{F}_B = Q\vec{v} \times \vec{B}$ 

 $\vec{B}$ 

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$$v_{x}(t) = -C_{2}\cos(\omega t) + C_{1}\sin(\omega t)$$
$$\omega = \frac{qB_{z}}{m}$$
$$v_{y}(t) = C_{1}\cos(\omega t) + C_{2}\sin(\omega t)$$

Integrate for positions:

$$\int_{x_o}^{x} dx = \int_{o}^{t} v_x(t) dt$$
$$x(t) - x_o = -\frac{C_2}{\omega} \sin(\omega t) - \frac{C_1}{\omega} (\cos(\omega t) - 1)$$

similarly:

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$$y(t) - y_o = \frac{C_1}{\omega} \sin(\omega t) - \frac{C_2}{\omega} (\cos(\omega t) - 1)$$