## **Fundamental Concepts**

Things you must know:

(1) Definition of and approximation for average velocity (and the position update formula)

(2) Definition of momentum

$$=\frac{1}{\sqrt{1-\left(|\vec{v}|/c\right)^2}}$$

- (3) The Momentum Principle (also, the momentum update formula and derivative form)
- (4) Definitions of total energy, rest energy, and kinetic energy of a particle

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(5) The Energy Principle - be able to apply to "point particle" systems and real systems

## Specific Results

 $x_f = x_i + v_{xi}\Delta t \qquad \qquad y_f = y_i + v_{yi}\Delta t - \frac{1}{2}g(\Delta t)^2$ Projectile Motion:  $v_{vf} = v_{vi} - g\Delta t$  $v_{xf} = v_{xi}$  $\vec{\mathbf{F}}_{\text{grav on 2 by 1}} = -G \frac{m_1 m_2}{\left|\vec{\mathbf{r}}\right|^2} \hat{\mathbf{r}} \qquad \qquad U_{\text{grav}} = -G \frac{m_1 m_2}{\left|\vec{\mathbf{r}}\right|}$  $|\vec{F}_{grav}| \approx mg$  near Earth's surface  $U_{grav} \approx mgy$  near Earth's surface  $U_{\rm elec} = \frac{1}{4\pi\varepsilon_0} \frac{q_1 q_2}{|\vec{\mathbf{r}}|}$  $\vec{\mathbf{F}}_{\text{elec on 2 by 1}} = \frac{1}{4\pi\epsilon_0} \frac{q_1 q_2}{\left|\vec{\mathbf{r}}\right|^2} \hat{\mathbf{r}}$  $\left| \vec{\mathbf{F}}_{\text{spring}} \right| = k_{s} \left| s \right|$  $U_{spring} = \frac{1}{2}k_s s^2$  $U_i \approx \frac{1}{2}k_s s^2 - E_m$  $\Delta E_{thermal} = mC\Delta T$  $\left|\vec{F}_{buoyancy}\right|$  = weight of displaced fluid  $\vec{\mathbf{F}}_{air} \approx -\frac{1}{2}C\rho Av^2 \hat{\mathbf{v}}$  $K \approx \frac{1}{2}mv^2 = \frac{p^2}{2m}$  for  $v \ll c$   $E^2 - (pc)^2 = (mc^2)^2$   $W = \vec{F} \cdot \Delta \vec{r}$  (small displacement)  $Y = \frac{k_{s,i}}{d}$  (micro)  $v = d \sqrt{\frac{k_{s,i}}{m}}$  $Y = \frac{F_T / A}{\Lambda L / L} \text{ (macro)}$  $\vec{\mathbf{F}}_{\perp} = |\vec{\mathbf{p}}| \frac{d\hat{\mathbf{p}}}{dt} = |\vec{\mathbf{p}}| \frac{|\vec{\mathbf{v}}|}{\mathbf{p}} \hat{\mathbf{n}}$  $\overline{F}_{\parallel} = \frac{d|\overline{p}|}{dt} \hat{p}$  $\omega = \sqrt{\frac{k_s}{m}}$  $T = \frac{2\pi}{\Omega}$  $x(t) = A\cos(\omega t)$  $\vec{\mathbf{r}}_{cm} = \frac{m_1 \vec{\mathbf{r}}_1 + m_1 \vec{\mathbf{r}}_1 + \dots}{m_1 + m_2 + \dots} \qquad \vec{\mathbf{P}}_{cm} \approx M \vec{\mathbf{v}}_{cm} \quad (v \ll c)$ Multiparticle Systems:  $K_{tot} = K_{trans} + K_{rel}$   $K_{trans} \approx \frac{1}{2}Mv_{cm}^2$   $(v \ll c)$   $K_{rel} = K_{rot} + K_{vib}$ **Physical Constants**  $a = 2 \times 10^8 m/s$  $a = 0.8 \text{ m/s}^2$  $C = 6.7 \times 10^{-11} \text{N} \text{m}^2 / k \alpha^2$ 

$$m_{\text{proton}} = 1.7 \times 10^{-27} \text{ kg} \qquad m_{\text{electron}} = 9 \times 10^{-31} \text{ kg} \qquad N_A = 6.02 \times 10^{23} \text{ atoms/mole}$$
  
$$e = 1.6 \times 10^{-19} \text{ C} \qquad 1/4\pi\epsilon_0 = 9 \times 10^9 \text{ N} \cdot \text{m}^2 / \text{C}^2 \qquad 1 \text{ eV} = 1.6 \times 10^{-19} \text{ J}$$